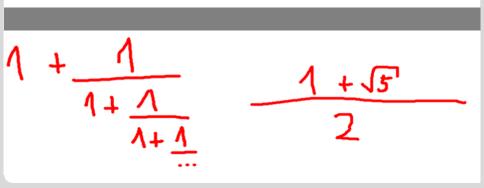




# **On-line Recognition of Handwritten Mathematical Symbols**

Bachelor's thesis of Martin Thoma

Martin Thoma | 5th of June, 2014



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## What is my Bachelor's thesis about?



- Recognition of handwritten mathematical symbols
- On-line recognition, not OCR!
- Given a series of points (x(t), y(t), b(t))I want to get the LATEX command.

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## Why did I work on this topic?



- $\[Mathbb{E}]$  Is easy as soon as you know the \commands.
- It's hard to find the LATEX command of single symbols.
- It's much harder to find complete formulas.

For now: recognition of isolated symbols.

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#### Normalizing

- Scaling
- Shifting
- Resampling

#### Noise reduction

- Smoothing (e.g. moving average)
- Dot reduction
- Filtering (by distance, speed or angle)
- Stroke connection

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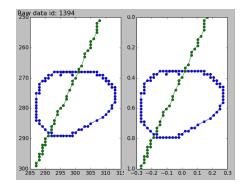


Normalizing

- Scaling
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- Resampling

#### Noise reduction

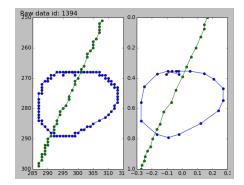
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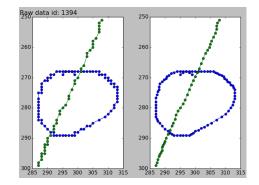
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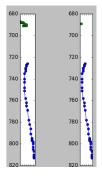
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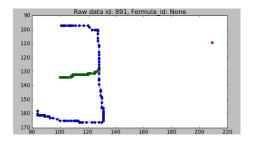
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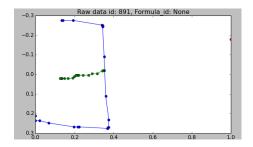
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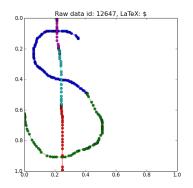
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- Normalizing
  - Scaling
  - Shifting
  - Resampling
- Noise reduction
  - Smoothing (e.g. moving average)
  - Dot reduction
  - Filtering (by distance, speed or angle)
  - Stroke connection



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#### Features



#### Local Features

- Coordinates
- Speed
- Binary pen pressure
- Direction
- Curvature
- Bitmap-environment
- Hat-Feature

#### **Global Features**

- # of dots  $(i, j, \dots, \dots)$
- # of strokes
- Center point coordinates
- Bitmap
- Bounding box (width, height, time)
- Re-curvature per stroke s  $\left(\frac{\mathsf{height}(s)}{\mathsf{length}(s)}\right)$

Ink

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## **Baseline Systems**



**Preprocessing:** Scaling, shifting and linear interpolation **Features:** Coordinates of 80 points (4 strokes with 20 points each) **Learning:** MLP, 1000 epochs, LR  $\eta = 0.1$ , Momentum  $\alpha = 0.1$ 

System	Topology	Class	ification e	error
System	Topology	TOP1	TOP3	MER
$B_1$	160:500:369	<b>23.34</b> %	6.80%	6.64 %
$B_2$	160:500:500:369	$\underline{21.51\%}$	5.75%	5.67%
$B_3$	160:500:500:500:369	21.93%	5.74%	5.64%

Table: Baseline systems with three different classification error measures. All errors were measured on the test set.

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Base s	symbol	equivalent symbols		
<b>A</b> TEX	Rendered	lat <sup>e</sup> x	Rendered	
\sum	$\sum$	\$\Sigma\$	$\Sigma$	
\prod	П	\$\Pi\$	Π	
		\$\sqcap\$		
\coprod	Ш	\$\amalg\$	Ш	
_		\$\sqcup\$		
\perp	$\perp$	\$\bot\$	$\perp$	
\models	=	\$\vDash\$	Þ	
I		\mid		
\Delta	$\dot{\Delta}$	\$\triangle\$	$\Delta$	
		\$\vartriangle\$	$\bigtriangleup$	

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Base sy	/mbol	equivalent symb	ols
lat <sup>E</sup> χ	Rendered	ATEX	Rendered
		\$\parallel\$	
∖ohm	$\Omega$	\$\Omega\$	Ω
\setminus	$\backslash$	\$\backslash\$	$\backslash$
\checked	$\checkmark$	\$\checkmark\$	$\checkmark$
\&	&	\$\with\$	&
\#	#	\$\sharp\$	#
\S	§	\$\mathsection\$	§
\nabla	$\nabla$	\triangledown	$\bigtriangledown$
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Base syn	nbol	equivalent s	ymbols
ĽΕχ	Rendered	₽T <sub>E</sub> X	Rendered
$\mathbb{R}$	$\mathbb{R}$	$\Delta R}$	$\mathbb{R}$
$\mathbb{Q}$	$\mathbb{Q}$	$\mathbb{Q}$	$\mathbb{Q}$
$\mathbb{Z}$	$\mathbb{Z}$	$\mathbb{Z}$	$\mathbb{Z}$
$\mathbb{A}$	$\mathcal{A}$	$\mathbf{A}$	A
$\mathbb{D}$	$\mathcal{D}$	$\mathbb{D}$	D
$\mathbb{N} $	$\mathcal{N}$	$\mathbb{N} $	$\mathcal{N}$
$\mathbb{R}$	${\mathcal R}$	$\mathbb{R}$	${\mathscr R}$
\propto	$\propto$	\$\varpropto\$	Q

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System	Classification error					
oystem	TOP1	change	TOP3	change	MER	change
$\begin{array}{c} \hline B_{1,\theta=5 \text{ px}} \\ B_{2,\theta=5 \text{ px}} \\ B_{3,\theta=5 \text{ px}} \end{array}$	23.27 %	-0.07 %	6.50 %	-0.30 %	6.37 %	-0.27 %
	21.20 %	-0.31 %	5.59 %	-0.16 %	5.50 %	-0.17 %
	21.80 %	-0.13 %	5.54 %	-0.20 %	5.47 %	-0.17 %
$\begin{array}{c} B_{1,\theta=10 \text{ px}} \\ B_{2,\theta=10 \text{ px}} \\ B_{3,\theta=10 \text{ px}} \end{array}$	23.17 %	-0.17 %	6.61 %	-0.19 %	6.47 %	-0.17 %
	20.97 %	-0.54 %	5.43 %	-0.32 %	5.34 %	-0.33 %
	21.34 %	-0.59 %	5.42 %	-0.32 %	5.33 %	-0.31 %
$\begin{array}{c} B_{1,\theta=20 \ \mathrm{px}} \\ B_{2,\theta=20 \ \mathrm{px}} \\ B_{3,\theta=20 \ \mathrm{px}} \end{array}$	22.81 %	-0.53 %	6.28 %	-0.52 %	6.19 %	-0.45 %
	21.61 %	0.10 %	5.79 %	0.04 %	5.69 %	0.02 %
	21.71 %	-0.22 %	5.55 %	-0.19 %	5.45 %	-0.19 %

Table: Models  $B_1$ - $B_4$  with additionally applied stroke connect algorithm.

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# Learning: Supervised layer-wise pretraining



System			Classifica	tion error		
oystem	TOP1	change	TOP3	change	MER	change
$B_1$	23.34 %		6.80%		6.64%	
$B_{2,p}$	19.89%	-1.62%	4.76%	-0.99%	4.68%	-0.99%
$B_{3,p}$	$\underline{19.43\%}$	-2.50%	4.64%	-1.10%	$\underline{4.54\%}$	-1.10%

Table: Supervised layer-wise pretraining, 1000 epochs per layer

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# **Optimized classifier**



**Preprocessing:** Connect strokes, scale, shift and linear interpolation **Features:** Coordinates of 80 points (4 strokes with 20 points each), re-curvature per stroke, ink, stroke count, aspect ratio **Learning:** MLP, 1000 epochs, LR  $\eta = 0.1$ , Momentum  $\alpha = 0.1$ , supervised layer-wise pretraining

System	Classification error					
	TOP1	change	TOP3	change	MER	change
$B_{1,c}$	20.96%	-2.38%	5.24%	-1.56%	5.13%	-1.51%
$B_{2,c}$	18.26%	-3.25%	4.07%	-1.68%	$\underline{3.98\%}$	-1.69%
$B_{3,c}$	$\underline{18.19\%}$	-3.74%	$\underline{4.06\%}$	-1.68%	3.99%	-1.65%

Table: Error rates of the complex recognizer systems.

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Two software projects were created:

- write-math.com: A website where on-line handwritten data gets collected and classified
- hwrt: The handwriting recognition toolkit is a Python project for handwriting recognition

This presentation and the bachelor's thesis will be at martin-thoma.com/write-math.

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- Server by RRZEicons
- Desktop Computer by Ed g2s, Ironbrother, Kierancassel and Msgj
- Server by Mimooh

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## **Thanks for Your Attention!**





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