

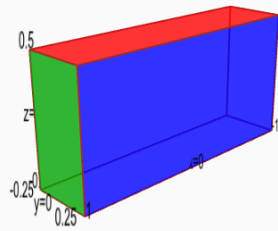
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Contents

```
show(cube(color=['red', 'blue', 'green'], frame_thickness=2,
          frame_color='brown', opacity=0.8).transform(scale=[2,1/2,1]), \
      frame=True)
```



```
print cube
#print(help(cube(frame_thickness=2, frame_color='brown', opacity=0.8)))
<function cube at 0x7eff06a26050>
```

Help on Graphics3dGroup in module sage.plot.plot3d.base object:

```
class Graphics3dGroup(Graphics3d)
|   File: sage/plot/plot3d/base.pyx (starting at line 1422)
|
|   This class represents a collection of 3d objects. Usually they are formed
|   implicitly by summing.
|
|   Method resolution order:
|       Graphics3dGroup
|       Graphics3d
|       sage.structure.sage_object.SageObject
|       __builtin__.object
```

```

| Methods defined here:
|
| __add__(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1441)
|
|     We override this here to make large sums more efficient.
|
|     EXAMPLES::
|
|         sage: G = sum(tetrahedron(opacity=1-t/11).translate(t, 0, 0) for t in
range(10))
|         sage: G
|         Graphics3d Object
|         sage: len(G.all)
|         10
|
|     We check that :trac:‘17258‘ is solved::
|
|         sage: g = point3d([0,-2,-2]); g += point3d([2,-2,-2])
|         sage: len(g.all)
|         2
|         sage: h = g + arrow([0,-2,-2], [2,-2,-2])
|         sage: len(g.all)
|         2
|         sage: g == h
|         False
|
| __init__(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1427)
|
|     EXAMPLES::
|
|         sage: sage.plot.plot3d.base.Graphics3dGroup([icosahedron(),
dodecahedron(opacity=.5)])
|         Graphics3d Object
|         sage: type(icosahedron() + dodecahedron(opacity=.5))
|         <class 'sage.plot.plot3d.base.Graphics3dGroup'>
|
| bounding_box(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1471)
|
|     Box that contains the bounding boxes of
|     all the objects that make up ‘‘self‘‘.
|
|     EXAMPLES::
|
|         sage: A = sphere((0,0,0), 5)
|         sage: B = sphere((1, 5, 10), 1)
|         sage: A.bounding_box()
|         ((-5.0, -5.0, -5.0), (5.0, 5.0, 5.0))

```

```

|         sage: B.bounding_box()
|         ((0.0, 4.0, 9.0), (2.0, 6.0, 11.0))
|         sage: (A+B).bounding_box()
|         ((-5.0, -5.0, -5.0), (5.0, 6.0, 11.0))
|         sage: (A+B).show(aspect_ratio=1, frame=True)
|
|         sage: sage.plot.plot3d.base.Graphics3dGroup([]).bounding_box()
|         ((0.0, 0.0, 0.0), (0.0, 0.0, 0.0))
|
| flatten(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1637)
|
|     Try to reduce the depth of the scene tree by consolidating groups
|     and transformations.
|
|     EXAMPLES::
|
|         sage: G = sum([circle((0, 0), t) for t in [1..10]], sphere()); G
|         Graphics3d Object
|         sage: G.flatten()
|         Graphics3d Object
|         sage: len(G.all)
|         2
|         sage: len(G.flatten().all)
|         11
|
| jmol_repr(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1602)
|
|     The jmol representation of a group is simply the concatenation of
|     the representation of its objects.
|
|     EXAMPLES::
|
|         sage: G = sphere() + sphere((1,2,3))
|         sage: G.jmol_repr(G.default_render_params())
|         [[['isosurface sphere_1  center {0.0 0.0 0.0} sphere 1.0\ncolor isosurface
| [102,102,255]'],
|          [['isosurface sphere_2  center {1.0 2.0 3.0} sphere 1.0\ncolor isosurface
| [102,102,255]']]]
|
| json_repr(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1529)
|
|     The JSON representation of a group is simply the concatenation of the
|     representations of its objects.
|
|     EXAMPLES::
|
|         sage: G = sphere() + sphere((1, 2, 3))
|         sage: G.json_repr(G.default_render_params())

```

```

|         [{"vertices:..."}], [{"vertices:..."}]]
|
| obj_repr(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1574)
|
|     The obj representation of a group is simply the concatenation of
|     the representation of its objects.
|
|     EXAMPLES::
|
|         sage: G = tetrahedron() + tetrahedron().translate(10, 10, 10)
|         sage: G.obj_repr(G.default_render_params())
|         [['g obj_1',
|          'usemtl ...',
|          ['v 0 0 1',
|           'v 0.942809 0 -0.333333',
|           'v -0.471405 0.816497 -0.333333',
|           'v -0.471405 -0.816497 -0.333333'],
|          ['f 1 2 3', 'f 2 4 3', 'f 1 3 4', 'f 1 4 2'],
|          []],
|         [['g obj_2',
|          'usemtl ...',
|          ['v 10 10 11',
|           'v 10.9428 10 9.66667',
|           'v 9.5286 10.8165 9.66667',
|           'v 9.5286 9.1835 9.66667'],
|          ['f 5 6 7', 'f 6 8 7', 'f 5 7 8', 'f 5 8 6'],
|          []]]
|
| set_texture(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1515)
|
|     EXAMPLES::
|
|         sage: G = dodecahedron(color='red', opacity=.5) + icosahedron((3, 0, 0),
color='blue')
|         sage: G
|         Graphics3d Object
|         sage: G.set_texture(color='yellow')
|         sage: G
|         Graphics3d Object
|
| tachyon_repr(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1542)
|
|     The tachyon representation of a group is simply the concatenation of
|     the representations of its objects.
|
|     EXAMPLES::
|
|         sage: G = sphere() + sphere((1,2,3))

```

```

|         sage: G.tachyon_repr(G.default_render_params())
|         [['Sphere center 0.0 0.0 0.0 Rad 1.0 texture...'],
|          ['Sphere center 1.0 2.0 3.0 Rad 1.0 texture...']]
|
| texture_set(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1616)
|
|     The texture set of a group is simply the union of the textures of
|     all its objects.
|
|     EXAMPLES::
|
|         sage: G = sphere(color='red') + sphere(color='yellow')
|         sage: [t for t in G.texture_set() if t.color == colors.red] # one red texture
|         [Texture(texture..., red, ff0000)]
|         sage: [t for t in G.texture_set() if t.color == colors.yellow] # one yellow
texture
|         [Texture(texture..., yellow, ffff00)]
|
|         sage: T = sage.plot.plot3d.texture.Texture('blue'); T
|         Texture(texture..., blue, 0000ff)
|         sage: G = sphere(texture=T) + sphere((1, 1, 1), texture=T)
|         sage: len(G.texture_set())
|         1
|
| transform(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1496)
|
|     Transforming this entire group simply makes a transform group with
|     the same contents.
|
|     EXAMPLES::
|
|         sage: G = dodecahedron(color='red', opacity=.5) + icosahedron(color='blue')
|         sage: G
|         Graphics3d Object
|         sage: G.transform(scale=(2,1/2,1))
|         Graphics3d Object
|         sage: G.transform(trans=(1,1,3))
|         Graphics3d Object
|
| x3d_str(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 1556)
|
|     The x3d representation of a group is simply the concatenation of
|     the representation of its objects.
|
|     EXAMPLES::
|
|         sage: G = sphere() + sphere((1,2,3))
|         sage: print G.x3d_str()

```

```

|         <Transform translation='0 0 0'>
|         <Shape><Sphere radius='1.0'></Appearance><Material diffuseColor='0.4 0.4 1.0'
shininess='1' specularColor='0.0 0.0 0.0'></Appearance></Shape>
|         </Transform>
|         <Transform translation='1 2 3'>
|         <Shape><Sphere radius='1.0'></Appearance><Material diffuseColor='0.4 0.4 1.0'
shininess='1' specularColor='0.0 0.0 0.0'></Appearance></Shape>
|         </Transform>
|
| -----
| Data descriptors defined here:
|
| __dict__
|     dictionary for instance variables (if defined)
|
| __weakref__
|     list of weak references to the object (if defined)
|
| -----
| Data and other attributes defined here:
|
| __qualname__ = 'Graphics3dGroup'
|
| -----
| Methods inherited from Graphics3d:
|
| __radd__(...)
|     x.__radd__(y) <==> y+x
|
| __str__(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 150)
|
|     EXAMPLES::
|
|         sage: S = sphere((0, 0, 0), 1)
|         sage: str(S)
|         'Graphics3d Object'
|
| aspect_ratio(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 213)
|
|     Set or get the preferred aspect ratio of 'self'.
|
|     INPUT:
|
|     - 'v' -- (default: 'None') must be a list or tuple of length three,
|       or the integer '1'. If no arguments are provided then the
|       default aspect ratio is returned.
|
|     EXAMPLES::

```

```

sage: D = dodecahedron()
sage: D.aspect_ratio()
[1.0, 1.0, 1.0]
sage: D.aspect_ratio([1,2,3])
sage: D.aspect_ratio()
[1.0, 2.0, 3.0]
sage: D.aspect_ratio(1)
sage: D.aspect_ratio()
[1.0, 1.0, 1.0]

default_render_params(...)
File: sage/plot/plot3d/base.pyx (starting at line 467)

Return an instance of RenderParams suitable for plotting this object.

EXAMPLES::

sage: type(dodecahedron().default_render_params())
<class 'sage.plot.plot3d.base.RenderParams'>

export_jmol(...)
File: sage/plot/plot3d/base.pyx (starting at line 651)

A jmol scene consists of a script which refers to external files.
Fortunately, we are able to put all of them in a single zip archive,
which is the output of this call.

EXAMPLES::

sage: out_file = tmp_filename(ext=".jmol")
sage: G = sphere((1, 2, 3), 5) + cube() + sage.plot.plot3d.shapes.Text("hi")
sage: G.export_jmol(out_file)
sage: import zipfile
sage: z = zipfile.ZipFile(out_file)
sage: z.namelist()
['obj_...pmesh', 'SCRIPT']

sage: print z.read('SCRIPT')
data "model list"
2
empty
Xx 0 0 0
Xx 5.5 5.5 5.5
end "model list"; show data
select *
wireframe off; spacefill off
set labelOffset 0 0
background [255,255,255]
spin OFF
moveto 0 -764 -346 -545 76.39
centerAt absolute {0 0 0}

```

```

zoom 100
frank OFF
set perspectivedepth ON
isosurface sphere_1 center {1.0 2.0 3.0} sphere 5.0
color isosurface [102,102,255]
pmesh obj_... "obj_...pmesh"
color pmesh [102,102,255]
select atomno = 1
color atom [102,102,255]
label "hi"
isosurface fullylit; pmesh o* fullylit; set antialiasdisplay on;

sage: print z.read(z.namelist()[0])
24
0.5 0.5 0.5
-0.5 0.5 0.5
...
-0.5 -0.5 -0.5
6
5
0
1
...

```

frame_aspect_ratio(...)

File: sage/plot/plot3d/base.pyx (starting at line 247)

Set or get the preferred frame aspect ratio of ‘self’.

INPUT:

- ‘v’ -- (default: ‘None’) must be a list or tuple of length three, or the integer ‘1’. If no arguments are provided then the default frame aspect ratio is returned.

EXAMPLES::

```

sage: D = dodecahedron()
sage: D.frame_aspect_ratio()
[1.0, 1.0, 1.0]
sage: D.frame_aspect_ratio([2,2,1])
sage: D.frame_aspect_ratio()
[2.0, 2.0, 1.0]
sage: D.frame_aspect_ratio(1)
sage: D.frame_aspect_ratio()
[1.0, 1.0, 1.0]

```

mtl_str(...)

File: sage/plot/plot3d/base.pyx (starting at line 877)

Return the contents of a .mtl file, to be used to provide coloring

information for an .obj file.

EXAMPLES::

```
sage: G = tetrahedron(color='red') + tetrahedron(color='yellow', opacity=0.5)
sage: print G.mtl_str()
newmtl ...
Ka 0.5 5e-06 5e-06
Kd 1.0 1e-05 1e-05
Ks 0.0 0.0 0.0
illum 1
Ns 1
d 1
newmtl ...
Ka 0.5 0.5 5e-06
Kd 1.0 1.0 1e-05
Ks 0.0 0.0 0.0
illum 1
Ns 1
d 0.5000000000000000
```

obj(...)

File: sage/plot/plot3d/base.pyx (starting at line 622)

An .obj scene file (as a string) containing the this object.

A .mtl file of the same name must also be produced for coloring.

EXAMPLES::

```
sage: from sage.plot.plot3d.shapes import ColorCube
sage: print ColorCube(1, ['red', 'yellow', 'blue']).obj()
g obj_1
usemtl ...
v 1 1 1
v -1 1 1
v -1 -1 1
v 1 -1 1
f 1 2 3 4
...
g obj_6
usemtl ...
v -1 -1 1
v -1 1 1
v -1 1 -1
v -1 -1 -1
f 21 22 23 24
```

rotate(...)

File: sage/plot/plot3d/base.pyx (starting at line 397)

Return ‘self’ rotated about the vector ‘v’ by ‘\theta’ radians.

EXAMPLES::

```
sage: from sage.plot.plot3d.shapes import Cone
sage: v = (1,2,3)
sage: G = arrow3d((0, 0, 0), v)
sage: G += Cone(1/5, 1).translate((0, 0, 2))
sage: C = Cone(1/5, 1, opacity=.25).translate((0, 0, 2))
sage: G += sum(C.rotate(v, pi*t/4) for t in [1..7])
sage: G.show(aspect_ratio=1)

sage: from sage.plot.plot3d.shapes import Box
sage: Box(1/3, 1/5, 1/7).rotate((1, 1, 1), pi/3).show(aspect_ratio=1)
```

rotateX(...)

File: sage/plot/plot3d/base.pyx (starting at line 417)

Return ‘self’ rotated about the ‘x’-axis by the given angle.

EXAMPLES::

```
sage: from sage.plot.plot3d.shapes import Cone
sage: G = Cone(1/5, 1) + Cone(1/5, 1, opacity=.25).rotateX(pi/2)
sage: G.show(aspect_ratio=1)
```

rotateY(...)

File: sage/plot/plot3d/base.pyx (starting at line 429)

Return ‘self’ rotated about the ‘y’-axis by the given angle.

EXAMPLES::

```
sage: from sage.plot.plot3d.shapes import Cone
sage: G = Cone(1/5, 1) + Cone(1/5, 1, opacity=.25).rotateY(pi/3)
sage: G.show(aspect_ratio=1)
```

rotateZ(...)

File: sage/plot/plot3d/base.pyx (starting at line 441)

Return ‘self’ rotated about the ‘z’-axis by the given angle.

EXAMPLES::

```
sage: from sage.plot.plot3d.shapes import Box
sage: G = Box(1/2, 1/3, 1/5) + Box(1/2, 1/3, 1/5, opacity=.25).rotateZ(pi/5)
sage: G.show(aspect_ratio=1)
```

save(...)

File: sage/plot/plot3d/base.pyx (starting at line 1334)

Save to file.

Save the graphic to an image file (of type: PNG, BMP, GIF, PPM, or TIFF) rendered using Tachyon, or pickle it (stored as an SOBJ so you can load it later) depending on the file extension you give the filename.

INPUT:

- ‘filename’ -- Specify where to save the image or object.
- ‘**kwargs’ -- When specifying an image file to be rendered by Tachyon, any of the viewing options accepted by show() are valid as keyword arguments to this function and they will behave in the same way. Accepted keywords include: ‘viewer’, ‘verbosity’, ‘figsize’, ‘aspect_ratio’, ‘frame_aspect_ratio’, ‘zoom’, ‘frame’, and ‘axes’. Default values are provided.

EXAMPLES::

```
sage: f = tmp_filename() + '.png'
sage: G = sphere()
sage: G.save(f)
```

We demonstrate using keyword arguments to control the appearance of the output image::

```
sage: G.save(f, zoom=2, figsize=[5, 10])
```

But some extra parameters don't make sense (like ‘viewer’, since rendering is done using Tachyon only). They will be ignored::

```
sage: G.save(f, viewer='jmol') # Looks the same
```

Since Tachyon only outputs PNG images, PIL will be used to convert to alternate formats::

```
sage: cube().save(tmp_filename(ext='.gif'))
```

save_image(...)

File: sage/plot/plot3d/base.pyx (starting at line 1312)

Save an image representation of self. The image type is determined by the extension of the filename. For example, this could be ‘.png’, ‘.jpg’, ‘.gif’, ‘.pdf’, ‘.svg’. Currently this is implemented by calling the :meth:‘save’ method of self, passing along all arguments and keywords.

.. Note::

Not all image types are necessarily implemented for all graphics types. See :meth:'save' for more details.

EXAMPLES::

```
sage: f = tmp_filename() + '.png'
sage: G = sphere()
sage: G.save_image(f)
```

scale(...)

File: sage/plot/plot3d/base.pyx (starting at line 373)

Return ``self`` scaled in the x, y, and z directions.

EXAMPLES::

```
sage: G = dodecahedron() + dodecahedron(opacity=.5).scale(2)
sage: G.show(aspect_ratio=1)
sage: G = icosahedron() + icosahedron(opacity=.5).scale([1, 1/2, 2])
sage: G.show(aspect_ratio=1)
```

TESTS::

```
sage: G = sphere((0, 0, 0), 1)
sage: G.scale(2)
Graphics3d Object
sage: G.scale(1, 2, 1/2).show(aspect_ratio=1)
sage: G.scale(2).bounding_box()
((-2.0, -2.0, -2.0), (2.0, 2.0, 2.0))
```

show(...)

File: sage/plot/plot3d/base.pyx (starting at line 1090)

INPUT:

- ``viewer`` -- string (default: 'jmol'), how to view the plot
 - * 'jmol': Interactive 3D viewer using Java
 - * 'tachyon': Ray tracer generates a static PNG image
 - * 'java3d': Interactive OpenGL based 3D
 - * 'canvas3d': Web-based 3D viewer powered by JavaScript and <canvas> (notebook only)
- ``filename`` -- string (default: a temp file); filename without extension to save the image file(s) to
- ``verbosity`` -- display information about rendering

```

the figure

- ‘‘figsize’’ -- (default: 5); x or pair [x,y] for
  numbers, e.g., [5,5]; controls the size of the output figure. E.g.,
  with Tachyon the number of pixels in each direction is 100 times
  figsize[0]. This is ignored for the jmol embedded renderer.

- ‘‘aspect_ratio’’ -- (default: "automatic") -- aspect
  ratio of the coordinate system itself. Give [1,1,1] to make spheres
  look round.

- ‘‘frame_aspect_ratio’’ -- (default: "automatic")
  aspect ratio of frame that contains the 3d scene.

- ‘‘zoom’’ -- (default: 1) how zoomed in

- ‘‘frame’’ -- (default: True) if True, draw a
  bounding frame with labels

- ‘‘axes’’ -- (default: False) if True, draw coordinate
  axes

- ‘‘**kwds’’ -- other options, which make sense for particular
  rendering engines

```

CHANGING DEFAULTS: Defaults can be uniformly changed by importing a dictionary and changing it. For example, here we change the default so images display without a frame instead of with one::

```

sage: from sage.plot.plot3d.base import SHOW_DEFAULTS
sage: SHOW_DEFAULTS['frame'] = False

```

This sphere will not have a frame around it::

```

sage: sphere((0,0,0))
Graphics3d Object

```

We change the default back::

```

sage: SHOW_DEFAULTS['frame'] = True

```

Now this sphere is enclosed in a frame::

```

sage: sphere((0,0,0))
Graphics3d Object

```

EXAMPLES: We illustrate use of the ‘‘aspect_ratio’’ option::

```

sage: x, y = var('x,y')
sage: p = plot3d(2*sin(x*y), (x, -pi, pi), (y, -pi, pi))
sage: p.show(aspect_ratio=[1,1,1])

```

This looks flattened, but filled with the plot::

```
sage: p.show(frame_aspect_ratio=[1,1,1/16])
```

This looks flattened, but the plot is square and smaller::

```
sage: p.show(aspect_ratio=[1,1,1], frame_aspect_ratio=[1,1,1/8])
```

This example shows indirectly that the defaults from :func:`~sage.plot.plot.plot` are dealt with properly::

```
sage: plot(vector([1,2,3]))
Graphics3d Object
```

We use the 'canvas3d' backend from inside the notebook to get a view of the plot rendered inline using HTML canvas::

```
sage: p.show(viewer='canvas3d')
```

From the command line, you probably want to specify an explicit filename::

```
sage: basedir = tmp_dir()
sage: basename = os.path.join(basedir, "xyz")
sage: p.show(filename=basename)
```

In this doctest, we see many files because we test various viewers::

```
sage: sorted(os.listdir(basedir))
['xyz-size500.spt', 'xyz-size500.spt.zip', 'xyz.mtl', 'xyz.obj', 'xyz.png']
```

tachyon(...)

File: sage/plot/plot3d/base.pyx (starting at line 545)

An tachyon input file (as a string) containing the this object.

EXAMPLES::

```
sage: print sphere((1, 2, 3), 5, color='yellow').tachyon()
begin_scene
resolution 400 400
    camera
    ...
plane
    center -2000 -1000 -500
    normal 2.3 2.4 2.0
TEXTURE
    AMBIENT 1.0 DIFFUSE 1.0 SPECULAR 1.0 OPACITY 1.0
    COLOR 1.0 1.0 1.0
```

```

|         TEXTFUNC 0
|         Texdef texture...
|         Ambient 0.333333333333 Diffuse 0.666666666667 Specular 0.0 Opacity 1
|         Color 1.0 1.0 0.0
|         TexFunc 0
|         Sphere center 1.0 -2.0 3.0 Rad 5.0 texture...
|     end_scene
|
|     sage: G = icosahedron(color='red') + sphere((1,2,3), 0.5, color='yellow')
|     sage: G.show(viewer='tachyon', frame=false)
|     sage: print G.tachyon()
|     begin_scene
|     ...
|     Texdef texture...
|     Ambient 0.333333333333 Diffuse 0.666666666667 Specular 0.0 Opacity 1
|     Color 1.0 1.0 0.0
|     TexFunc 0
|     TRI V0 ...
|     Sphere center 1.0 -2.0 3.0 Rad 0.5 texture...
|     end_scene
|
| testing_render_params(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 478)
|
|     Return an instance of RenderParams suitable for testing this object.
|
|     In particular, it opens up '/dev/null' as an auxiliary zip
|     file for jmol.
|
|     EXAMPLES::
|
|         sage: type(dodecahedron().testing_render_params())
|         <class 'sage.plot.plot3d.base.RenderParams'>
|
| translate(...)
|     File: sage/plot/plot3d/base.pyx (starting at line 347)
|
|     Return “self” translated by the given vector (which can be
|     given either as a 3-iterable or via positional arguments).
|
|     EXAMPLES::
|
|         sage: icosahedron() + sum(icosahedron(opacity=0.25).translate(2*n, 0, 0) for n
in [1..4])
|         Graphics3d Object
|         sage: icosahedron() + sum(icosahedron(opacity=0.25).translate([-2*n, n, n^2])
for n in [1..4])
|         Graphics3d Object
|
|     TESTS::

```

```

|         sage: G = sphere((0, 0, 0), 1)
|         sage: G.bounding_box()
|         ((-1.0, -1.0, -1.0), (1.0, 1.0, 1.0))
|         sage: G.translate(0, 0, 1).bounding_box()
|         ((-1.0, -1.0, 0.0), (1.0, 1.0, 2.0))
|         sage: G.translate(-1, 5, 0).bounding_box()
|         ((-2.0, 4.0, -1.0), (0.0, 6.0, 1.0))
|
|     viewpoint(...)
|         File: sage/plot/plot3d/base.pyx (starting at line 453)
|
|         Return the viewpoint of this plot.
|
|         Currently only a stub for x3d.
|
|         EXAMPLES::
|
|             sage: type(dodecahedron().viewpoint())
|             <class 'sage.plot.plot3d.base.Viewpoint'>
|
|     x3d(...)
|         File: sage/plot/plot3d/base.pyx (starting at line 494)
|
|         An x3d scene file (as a string) containing the this object.
|
|         EXAMPLES::
|
|             sage: print sphere((1, 2, 3), 5).x3d()
|             <X3D version='3.0' profile='Immersive' xmlns:xsd='http://www.w3.org/2001
|/XMLSchema-instance' xsd:noNamespaceSchemaLocation='
|http://www.web3d.org/specifications/x3d-3.0.xsd '>
|             <head>
|             <meta name='title' content='sage3d' />
|             </head>
|             <Scene>
|             <Viewpoint position='0 0 6' />
|             <Transform translation='1 2 3'>
|             <Shape><Sphere radius='5.0' /><Appearance><Material diffuseColor='0.4 0.4 1.0'
|shininess='1' specularColor='0.0 0.0 0.0' /></Appearance></Shape>
|             </Transform>
|             </Scene>
|             </X3D>
|
|             sage: G = icosahedron() + sphere((0,0,0), 0.5, color='red')
|             sage: print G.x3d()
|             <X3D version='3.0' profile='Immersive' xmlns:xsd='http://www.w3.org/2001
|/XMLSchema-instance' xsd:noNamespaceSchemaLocation='
|http://www.web3d.org/specifications/x3d-3.0.xsd '>
|             <head>
|             <meta name='title' content='sage3d' />
|             </head>

```



```

|         <Scene>
|         <Viewpoint position='0 0 6' />
|         <Shape>
|         <IndexedFaceSet coordIndex='...'>
|             <Coordinate point='...' />
|         </IndexedFaceSet>
|         <Appearance><Material diffuseColor='0.4 0.4 1.0' shininess='1'
specularColor='0.0 0.0 0.0' /></Appearance></Shape>
|         <Transform translation='0 0 0'>
|         <Shape><Sphere radius='0.5' /><Appearance><Material diffuseColor='1.0 0.0 0.0'
shininess='1' specularColor='0.0 0.0 0.0' /></Appearance></Shape>
|         </Transform>
|         </Scene>
|         </X3D>

```

Data descriptors inherited from Graphics3d:

```

| texture
|     File: sage/plot/plot3d/base.pxd (starting at line 5)

```

Data and other attributes inherited from Graphics3d:

```

| __new__ = <built-in method __new__ of type object>
|     T.__new__(S, ...) -> a new object with type S, a subtype of T

```

Methods inherited from sage.structure.sage_object.SageObject:

```

| __hash__(...)
|     File: sage/structure/sage_object.pyx (starting at line 230)

```

```

| __repr__(...)
|     File: sage/structure/sage_object.pyx (starting at line 124)

```

Default method for string representation.

.. NOTE::

Do not overwrite this method. Instead, implement
a ‘_repr_’ (single underscore) method.

EXAMPLES:

By default, the string representation coincides with
the output of the single underscore ‘_repr_’::

```

| sage: P.<x> = QQ[]
| sage: repr(P) == P._repr_() #indirect doctest
| True

```

```

|
| Using :meth:‘rename‘, the string representation can
| be customized::
|
|     sage: P.rename('A polynomial ring')
|     sage: repr(P) == P._repr_()
|     False
|
| The original behaviour is restored with :meth:‘reset_name‘::
|
|     sage: P.reset_name()
|     sage: repr(P) == P._repr_()
|     True
|
| category(...)
|     File: sage/structure/sage_object.pyx (starting at line 400)
|
| db(...)
|     File: sage/structure/sage_object.pyx (starting at line 371)
|
|     Dumps self into the Sage database. Use db(name) by itself to
|     reload.
|
|     The database directory is ‘‘$HOME/.sage/db‘‘
|
| dump(...)
|     File: sage/structure/sage_object.pyx (starting at line 343)
|
|     Same as self.save(filename, compress)
|
| dumps(...)
|     File: sage/structure/sage_object.pyx (starting at line 349)
|
|     Dump ‘‘self‘‘ to a string ‘‘s‘‘, which can later be reconstituted
|     as ‘‘self‘‘ using ‘‘loads(s)‘‘.
|
|     There is an optional boolean argument ‘‘compress‘‘ which defaults to ‘‘True‘‘.
|
|     EXAMPLES::
|
|         sage: O=SageObject(); O.dumps()
|         'x\x9ck'J.NL0\xd5+.)*M.)-\x02\xb2\x80\xdc\xfc\xfc\xa4\xac\xd4\xe4\x12\xae'
|         \xdb\x1f\xc2,d\xd4l,d\xd2\x03\x00\xb7X\x10\xf1'
|         sage: O.dumps(compress=False)
|         '\x80\x02csage.structure.sage_object\nSageObject\nq\x01)\x81q\x02.'
|
| parent(...)
|     File: sage/structure/sage_object.pyx (starting at line 435)
|
|     Return the type of ‘‘self‘‘ to support the coercion framework.
|

```

EXAMPLES::

```
sage: t = log(sqrt(2) - 1) + log(sqrt(2) + 1); t
log(sqrt(2) + 1) + log(sqrt(2) - 1)
sage: u = t.maxima_methods()
sage: u.parent()
<class 'sage.symbolic.maxima_wrapper.MaximaWrapper'>
```

rename(...)

File: sage/structure/sage_object.pyx (starting at line 47)

Change self so it prints as x, where x is a string.

.. NOTE::

This is *only* supported for Python classes that derive from SageObject.

EXAMPLES::

```
sage: x = PolynomialRing(QQ, 'x', sparse=True).gen()
sage: g = x^3 + x - 5
sage: g
x^3 + x - 5
sage: g.rename('a polynomial')
sage: g
a polynomial
sage: g + x
x^3 + 2*x - 5
sage: h = g^100
sage: str(h)[:20]
'x^300 + 100*x^298 - '
sage: h.rename('x^300 + ...')
sage: h
x^300 + ...
```

Real numbers are not Python classes, so rename is not supported::

```
sage: a = 3.14
sage: type(a)
<type 'sage.rings.real_mpfr.RealLiteral'>
sage: a.rename('pi')
Traceback (most recent call last):
...
NotImplementedError: object does not support renaming: 3.140000000000000
```

.. NOTE::

The reason C-extension types are not supported by default is if they were then every single one would have to carry around an extra attribute, which would be slower and waste

```

|         a lot of memory.
|
|         To support them for a specific class, add a
|         ‘‘cdef public __custom_name’’ attribute.
|
| reset_name(...)
|     File: sage/structure/sage_object.pyx (starting at line 104)
|
|     Remove the custrom name of an object.
|
|     EXAMPLES::
|
|         sage: P.<x> = QQ[]
|         sage: P
|         Univariate Polynomial Ring in x over Rational Field
|         sage: P.rename('A polynomial ring')
|         sage: P
|         A polynomial ring
|         sage: P.reset_name()
|         sage: P
|         Univariate Polynomial Ring in x over Rational Field
|
| version(...)
|     File: sage/structure/sage_object.pyx (starting at line 303)
|
|     The version of Sage.
|
|     Call this to save the version of Sage in this object.
|     If you then save and load this object it will know in what
|     version of Sage it was created.
|
|     This only works on Python classes that derive from SageObject.
None

```